

Transition path theory

July 09, 2025

Reminder

- 1 **Exercises:** solve 8 – 10 questions. Submission deadline: **23.07.2025**
- 2 **Course project:** Select one topic to conduct numerical experiment, and write a short report. Submission deadline: **27.07.2025**
- 3 give a 10-15 min **presentation**. Date: 11.07.2025 or 18.07.2025.

Part 1: Transition paths in the zero-temperature limit

Brownian dynamics

Brownian dynamics

- 1 Brownian dynamics in \mathbb{R}^d

$$dX_t = -\nabla V(X_t) dt + \sqrt{2\epsilon} dB_t, \quad t \geq 0,$$

where $\epsilon > 0$ is a constant.

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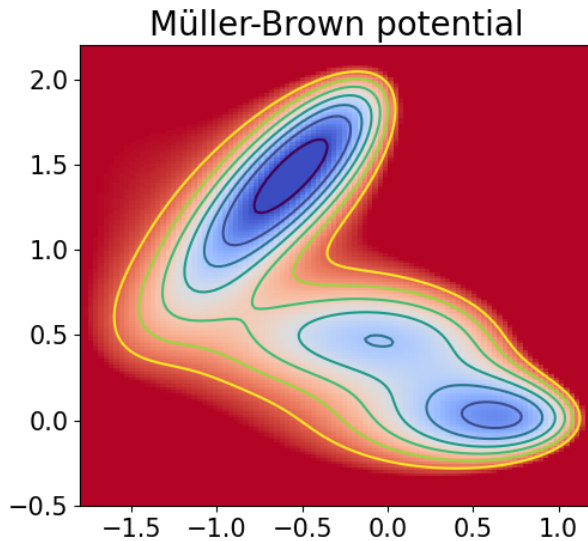
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- 3 Assume that V has multiple local minima.

Example



Wentzell-Freidlin theory and minimal energy path

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1 For a subset B in path space, we have

$$\lim_{\epsilon \rightarrow 0} \epsilon \ln P(B) = - \min_{\varphi \in B} I_T(\varphi) \iff P(B) \approx \exp \left(- \frac{1}{\epsilon} \min_{\varphi \in B} I_T(\varphi) \right).$$

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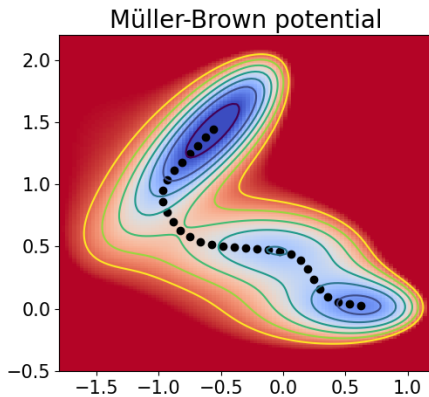
$$I_T(\varphi) = \frac{1}{4} \int_0^T \left| \dot{\varphi}(t) + \nabla V(\varphi(t)) \right|^2 dt.$$

- 3 Minimizing action \implies Minimal energy path (MEP):

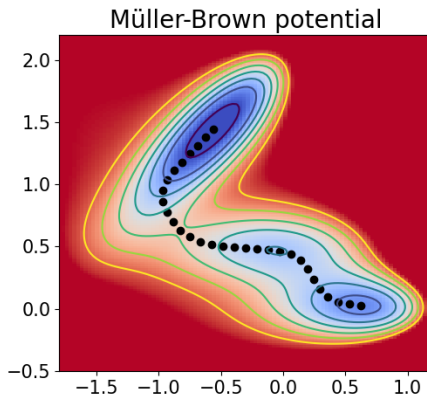
$$\begin{aligned} \varphi(T_1) &= a, \quad \varphi(T^*) = c, \quad \varphi(T_2) = b, \\ \dot{\varphi}(t) &= \begin{cases} \nabla V(\varphi(t)), & T_1 < t < T^*, \\ -\nabla V(\varphi(t)), & T^* < t < T_2. \end{cases} \end{aligned}$$

Lower bound of action is achieved as $T_1 \rightarrow -\infty, T_2 \rightarrow +\infty$.

Example of MEP



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At low temperature, transition paths concentrate on a single path (MEP).

Part 2: Commitor

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3 Infinitesimal generator:

$$\mathcal{L}f = -\nabla V \cdot \nabla f + \frac{1}{\beta} \Delta f.$$

Sets A and B

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Goal: to study the transition of X_t from A to B .

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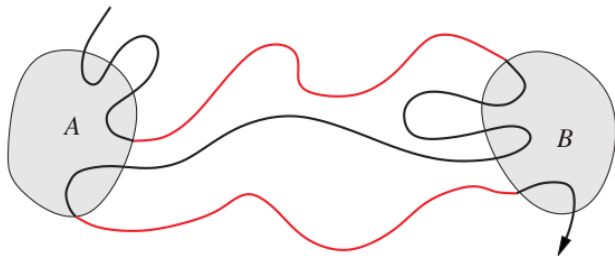
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Definition (Forward committor)

$$q(x) = P(\tau_{B,x} < \tau_{A,x}), \quad x \in \mathbb{R}^d.$$

Illustration



Committer equation

Proposition

The committor $q(x) = P(\tau_{B,x} < \tau_{A,x})$ solves

$$\mathcal{L}q = 0, \quad \text{on } (A \cup B)^c$$

$$q|_{\partial A} = 0, \quad q|_{\partial B} = 1,$$

where $\mathcal{L} = -\nabla V \cdot \nabla + \frac{1}{\beta} \Delta$ is the generator.

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Proof.

- 1 Applying Ito's formula and taking expectation

$$\implies \mathbb{E}(q(X_t) \mid X_0 = x) = q(x) + \int_0^t \mathbb{E}(\mathcal{L}q(X_s) \mid X_0 = x) ds.$$

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- 2 show $\mathbb{E}(q(X_t) \mid X_0 = x) = q(x) \implies \int_0^t \mathbb{E}(\mathcal{L}q(X_s) \mid X_0 = x) ds = 0.$



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Therefore, q solves the minimization problem

$$\min_f \left(\frac{1}{\beta} \int_{(A \cup B)^c} |\nabla f(x)|^2 \pi(x) dx \right)$$

among all C^1 -smooth $f : (A \cup B)^c \rightarrow \mathbb{R}$ such that $f|_{\partial A} = 0$ and $f|_{\partial B} = 1$.

Part 3: Transition path theory (TPT)

Random times

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$$\sigma_A^{(k)} = \sup \{t \mid \tau_A^{(k)} < t < \tau_B^{(k)}, X_t \in A\}, \quad k \geq 1.$$

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Trajectory segment that came from A and goes to B without returning to A .

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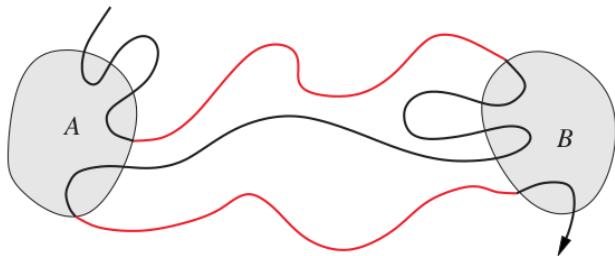
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- 2 $[t_1, t_2]$ corresponds to a reactive segment, if and only if

$$X_{t_1} \in A, \quad X_{t_2} \in B, \quad \text{and } X_t \in (A \cup B)^c, \quad \forall t_1 < t < t_2.$$

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$$t_{AB}^R = \lim_{T \rightarrow +\infty} \frac{\sum_{k=1}^{M_T} (\tau_B^{(k)} - \sigma_A^{(k)})}{M_T}.$$

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- 1 q^- is the forward committor for the time-reversal of X_t from B to A .
- 2 For Brownian dynamics, $q^-(x) = 1 - q(x)$.

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3 Brownian dynamics:

$$q^- = 1 - q \implies \pi^R(x) = Z_{AB}^{-1} \pi(x) (1 - q(x)) q(x).$$

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Lemma

$$k_{AB} = k_{BA}.$$

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- 2 Represent $q : \mathbb{R}^d \rightarrow [0, 1]$ by neural networks.
- 3 Loss function = objective + two penalty terms for boundary conditions.

Loss function for learning committor

$$k_{AB} = \frac{1}{\beta} \int_{(A \cup B)^c} |\nabla q(x)|^2 \pi(x) dx = \min_f \left(\frac{1}{\beta} \int_{(A \cup B)^c} |\nabla f(x)|^2 \pi(x) dx \right),$$

where $f|_{\partial A} = 0$ and $f|_{\partial B} = 1$.

- 1 States X_1, X_2, \dots, X_N are sampled from a long trajectory.
- 2 Represent $q : \mathbb{R}^d \rightarrow [0, 1]$ by neural networks.
- 3 Loss function = objective + two penalty terms for boundary conditions.

$$\begin{aligned} \text{Loss}(q) = & \frac{1}{\beta N} \sum_{n=1}^N |\nabla q(X_n)|^2 \mathbb{1}_{(A \cup B)^c}(X_n) \\ & + \frac{\lambda_1}{N} \sum_{n=1}^N (|q(X_n)|^2 \mathbb{1}_A(X_n)) + \frac{\lambda_2}{N} \sum_{n=1}^N (|q(X_n) - 1|^2 \mathbb{1}_B(X_n)). \end{aligned}$$

where $\lambda_1, \lambda_2 > 0$ are tunable parameters.

Part 4: Committor for Markov chains

Markov chains

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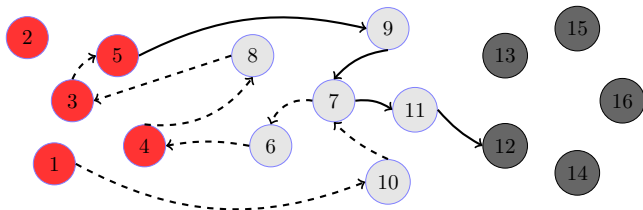
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Proposition

The committor q solves

$$\begin{cases} \sum_{j=1}^m P_{ij} q_j = q_i, & i \in (A \cup B)^c, \\ q_i = 0, & i \in A, \\ q_i = 1, & i \in B. \end{cases}$$

Example



Example

